

Fig. 1

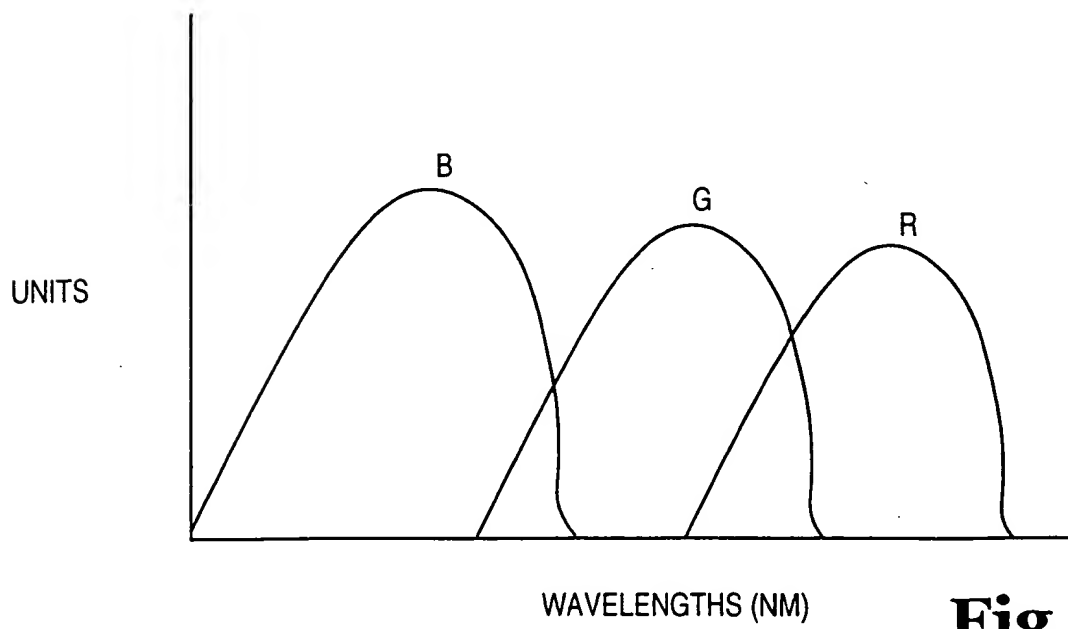


Fig. 2

A schematic diagram of a system for measuring the shape of a curved surface. The system includes a **COMPUTER** (10) connected via a cable (20) to a sensor assembly (16). The sensor assembly consists of a rectangular block (18) and a smaller rectangular block (16) mounted on a curved surface (12). The curved surface (12) is part of a larger structure (5) that has a triangular cross-section. The triangular cross-section is defined by two lines (14) meeting at a point, with a vertical line (5) extending from the base. The curved surface (12) is the arc of the circle formed by the intersection of the two lines (14) and the vertical line (5). The sensor assembly (16) is positioned to measure the curvature of the surface (12).

Fig. 3

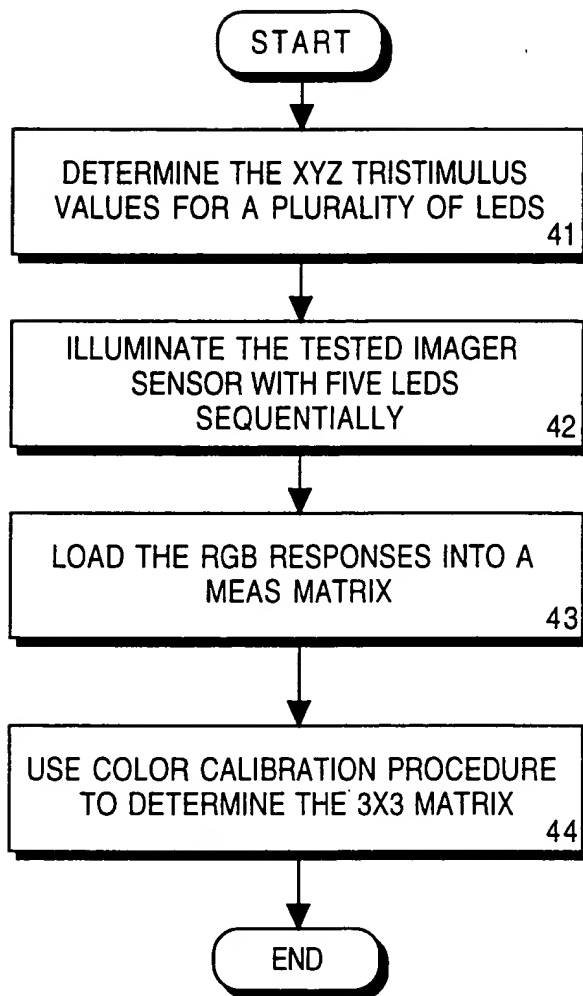


Fig. 4

1. **Introduction**
 2. **Background**
 3. **Methodology**
 4. **Results**
 5. **Discussion**
 6. **Conclusion**
 7. **References**
 8. **Appendix**
 9. **Index**
 10. **Table of Contents**
 11. **Abstract**
 12. **Summary**
 13. **Key Words**
 14. **Keywords**
 15. **Subject Headings**
 16. **Classification**
 17. **Indexing**
 18. **Keywords**
 19. **Subject Headings**
 20. **Classification**
 21. **Indexing**
 22. **Keywords**
 23. **Subject Headings**
 24. **Classification**
 25. **Indexing**
 26. **Keywords**
 27. **Subject Headings**
 28. **Classification**
 29. **Indexing**
 30. **Keywords**
 31. **Subject Headings**
 32. **Classification**
 33. **Indexing**
 34. **Keywords**
 35. **Subject Headings**
 36. **Classification**
 37. **Indexing**
 38. **Keywords**
 39. **Subject Headings**
 40. **Classification**
 41. **Indexing**
 42. **Keywords**
 43. **Subject Headings**
 44. **Classification**
 45. **Indexing**
 46. **Keywords**
 47. **Subject Headings**
 48. **Classification**
 49. **Indexing**
 50. **Keywords**
 51. **Subject Headings**
 52. **Classification**
 53. **Indexing**
 54. **Keywords**
 55. **Subject Headings**
 56. **Classification**
 57. **Indexing**
 58. **Keywords**
 59. **Subject Headings**
 60. **Classification**
 61. **Indexing**
 62. **Keywords**
 63. **Subject Headings**
 64. **Classification**
 65. **Indexing**
 66. **Keywords**
 67. **Subject Headings**
 68. **Classification**
 69. **Indexing**
 70. **Keywords**
 71. **Subject Headings**
 72. **Classification**
 73. **Indexing**
 74. **Keywords**
 75. **Subject Headings**
 76. **Classification**
 77. **Indexing**
 78. **Keywords**
 79. **Subject Headings**
 80. **Classification**
 81. **Indexing**
 82. **Keywords**
 83. **Subject Headings**
 84. **Classification**
 85. **Indexing**
 86. **Keywords**
 87. **Subject Headings**
 88. **Classification**
 89. **Indexing**
 90. **Keywords**
 91. **Subject Headings**
 92. **Classification**
 93. **Indexing**
 94. **Keywords**
 95. **Subject Headings**
 96. **Classification**
 97. **Indexing**
 98. **Keywords**
 99. **Subject Headings**
 100. **Classification**
 101. **Indexing**
 102. **Keywords**
 103. **Subject Headings**
 104. **Classification**
 105. **Indexing**
 106. **Keywords**
 107. **Subject Headings**
 108. **Classification**
 109. **Indexing**
 110. **Keywords**
 111. **Subject Headings**
 112. **Classification**
 113. **Indexing**
 114. **Keywords**
 115. **Subject Headings**
 116. **Classification**
 117. **Indexing**
 118. **Keywords**
 119. **Subject Headings**
 120. **Classification**
 121. **Indexing**
 122. **Keywords**
 123. **Subject Headings**
 124. **Classification**
 125. **Indexing**
 126. **Keywords**
 127. **Subject Headings**
 128. **Classification**
 129. **Indexing**
 130. **Keywords**
 131. **Subject Headings**
 132. **Classification**
 133. **Indexing**
 134. **Keywords**
 135. **Subject Headings**
 136. **Classification**
 137. **Indexing**
 138. **Keywords**
 139. **Subject Headings**
 140. **Classification**
 141. **Indexing**
 142. **Keywords**
 143. **Subject Headings**
 144. **Classification**
 145. **Indexing**
 146. **Keywords**
 147. **Subject Headings**
 148. **Classification**
 149. **Indexing**
 150. **Keywords**
 151. **Subject Headings**
 152. **Classification**
 153. **Indexing**
 154. **Keywords**
 155. **Subject Headings**
 156. **Classification**
 157. **Indexing**
 158. **Keywords**
 159. **Subject Headings**
 160. **Classification**
 161. **Indexing**
 162. **Keywords**
 163. **Subject Headings**
 164. **Classification**
 165. **Indexing**
 166. **Keywords**
 167. **Subject Headings**
 168. **Classification**
 169. **Indexing**
 170. **Keywords**
 171. **Subject Headings**
 172. **Classification**
 173. **Indexing**
 174. **Keywords**
 175. **Subject Headings**
 176. **Classification**
 177. **Indexing**
 178. **Keywords**
 179. **Subject Headings**
 180. **Classification**
 181. **Indexing**
 182. **Keywords**
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 185. **Indexing**
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 188. **Classification**
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 193. **Indexing**
 194. **Keywords**
 195. **Subject Headings**
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 197. **Indexing**
 198. **Keywords**
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 207. **Subject Headings**
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 209. **Indexing**
 210. **Keywords**
 211. **Subject Headings**
 212. **Classification**
 213. **Indexing**
 214. **Keywords**
 215. **Subject Headings**
 216. **Classification**
 217. **Indexing**
 218. **Keywords**
 219. **Subject Headings**
 220. **Classification**
 221. **Indexing**
 222. **Keywords**
 223. **Subject Headings**
 224. **Classification**
 225. **Indexing**
 226. **Keywords**
 227. **Subject Headings**
 228. **Classification**
 229. **Indexing**
 230. **Keywords**
 231. **Subject Headings**
 232. **Classification**
 233. **Indexing**
 234. **Keywords**
 235. **Subject Headings**
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 237. **Indexing**
 238. **Keywords**
 239. **Subject Headings**
 240. **Classification**
 241. **Indexing**
 242. **Keywords**
 243. **Subject Headings**
 244. **Classification**
 245. **Indexing**
 246. **Keywords**
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 249. **Indexing**
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 251. **Subject Headings**



[illegible]

Fig. 6

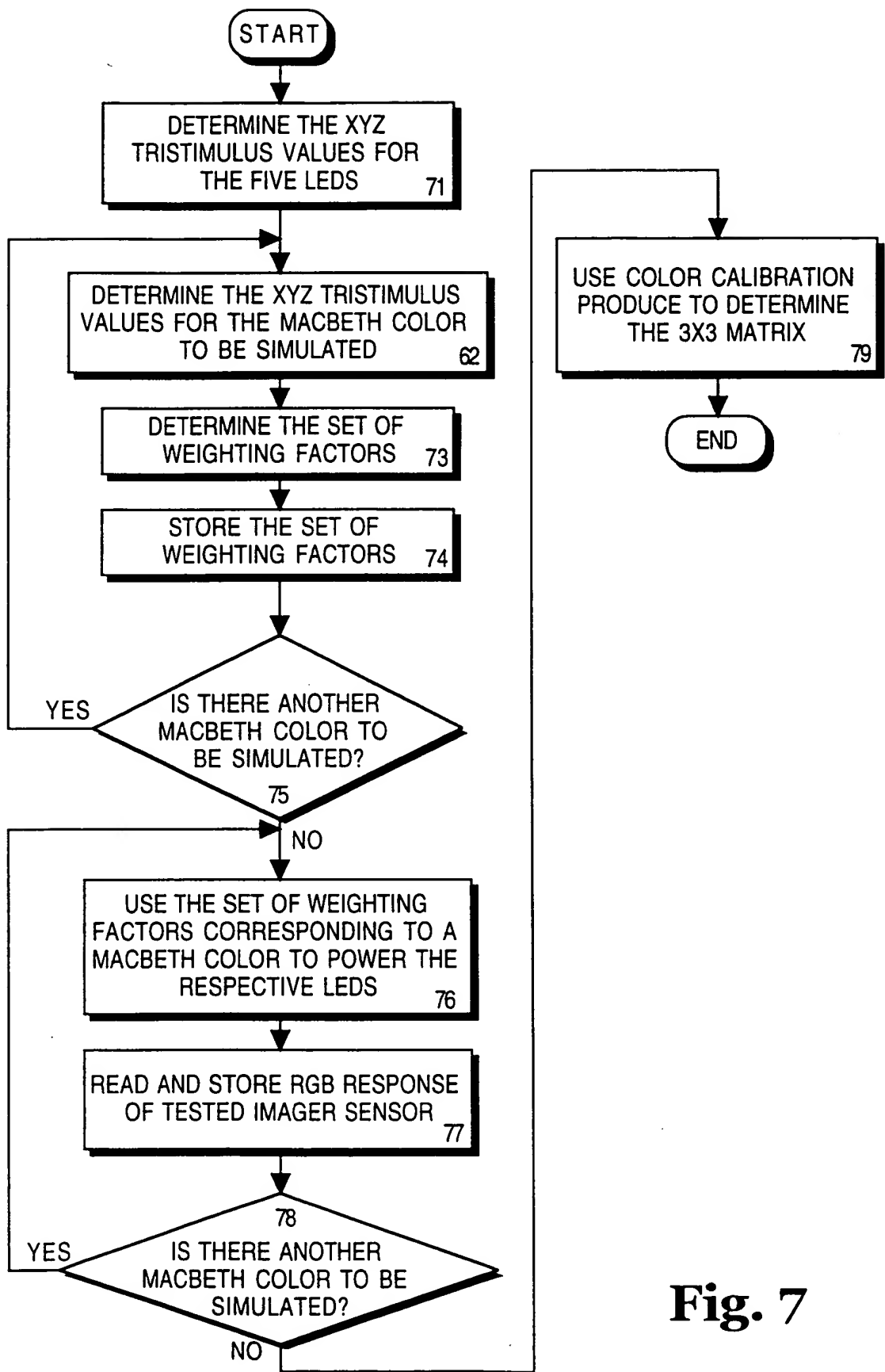


Fig. 7



DETERMINE THE RGB OFFSETS OF THE TESTED IMAGER DEVICE

81

ILLUMINATE THE TESTED IMAGER
DEVICE WITH FIVE LEDS SEQUENTIALLY

82

STORE THE RGB RESPONSES OF THE FIVE LEDS

83

COMPUTE THE SETS OF LED WEIGHTING
FACTORS ASSOCIATED WITH EACH OF
THE 24 MACBETH COLORS 84

84

APPLY THE COMPUTED SETS OF LED
WEIGHTING FACTORS TO THE STORED
RGB RESPONSES OF THE FIVE LEDS

85

USE COLOR CALIBRATION PROCEDURE
TO DETERMINE THE 3X3 MATRIX

86

```

graph TD
    A[Find a number] --> B{Is it 100?}
    B --> C{Is it 10?}
    C --> D{Is it 1?}
    D --> E[END]
  
```

Fig. 8

THE UNIVERSITY OF CHICAGO